

# Butterfly Valves

VA-18  
VA-19  
VA-20



## Design Features:

- Heavy Duty One Piece wafer Body Design.
- Top Flange Drilled to fit ISO 5211 dimensions.
- Semi Lugged Body Design with Guiding Holes for Better Alignment.
- Heavy Duty Square Grooved Disc/Stem Connections.
- Extended Neck Serves for 50mm(2") piping insulation from line media.
- Blow Out Proof Stem Sealing Design.
- Hard Backed Rubber Liner Design for Field Replacement.
- Moulded Ring seals on Liner to serve as flange gaskets.
- Sliding Bearing for minimize operating torques.

## Conformity to Standard & Codes: Applications

### Design Standard:

API 609, BS 5155, ISO 5211

### Face to Face Dimension:

API 609

### End Detail:

ASME B16.5 (Suitable for insertion between PN10/ PN16/ #150/ BS-10 Table D/ E Flanges)

### Valve Testing:

API 598

• HVAC

• Sugar

• Pulp and Paper

• Pharmaceutical

• Chemical and Petro Chemical

• Irrigation Systems

• Sewage Plants

• Food Processing

• Water Work Systems

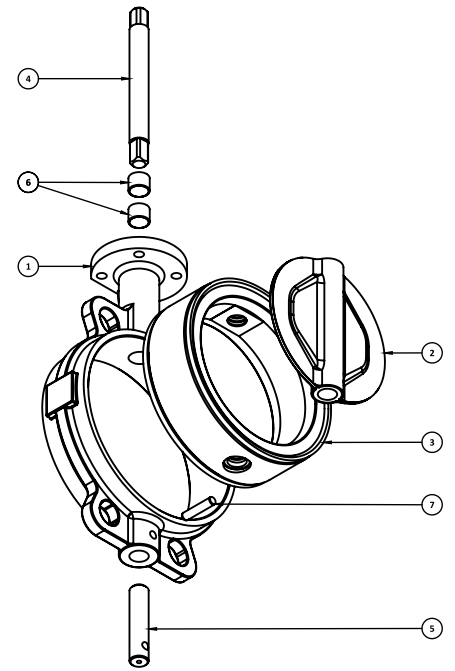


IS : 779  
CM/L NO.: 9503172

## PART LIST

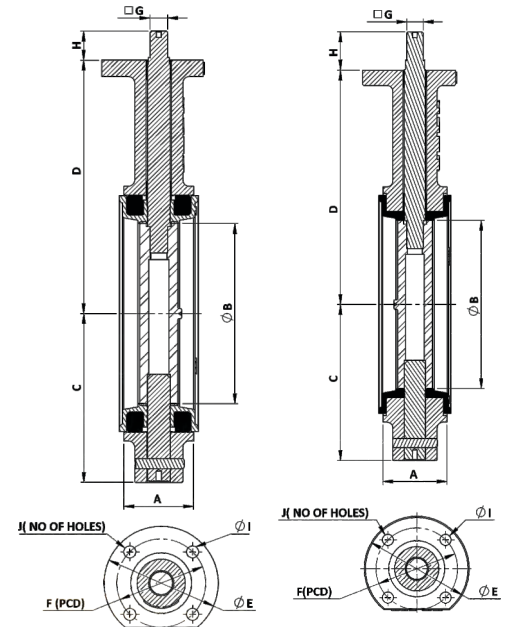
S. NO.	PART NAME	MATERIAL	SPECIFICATION	QTY.
1.	BODY	CAST IRON / DUCTILE IRON	IS210 GR. FG200/220 / ASTM A536 GR. 65-45-12/60-40-18	1
2.	DISC	DUCTILE IRON / STAINLESS STEEL	ASTM A536 GR. 65-45-12/60-40-18 / ASTM A351 GR. CF8/CF8M	1
3.	RUBBER SUPPORTED BACK-UP RING	PLASTIC/METAL + RUBBER	BACKLITE/ALUMINUM + NBR/EPDM	1
4.	MAIN STEM	STAINLESS STEEL	ASTM A 276 GR. 410/304/316	1
5.	PIVOT STEM	STAINLESS STEEL	ASTM A 276 GR. 410/304/316	1
6.	SELF LUBRICATED BUSH	STEEL + BRNZ + PTFE	CARBON STEEL BACKING + SINTERED BRONZE & PTFE	2
7.	DOWEL PIN	CARBON STEEL	ASTM A105	1
8.	FASTNERS	STAINLESS STEEL	SS201	--

Note: 1. Special Seat Material like PTFE lined EPDM/NBR, Body Moulded Fixed Seat, Silicon, Viton and UHMWPE Available on Demand.  
 2. Special Coatings available on Demand.  
 3. Contact Technical Team for Any Kind of Special Material.



## DIMENSIONS

SIZE	INCH	A	B	C	D	E	F	G	H	I	J
DN32	1¼"	33	32	73	109	65	50	9.5	10	7.5	4
DN40	1½"	33	40	73	109	65	50	9.5	10	7.5	4
DN50	2"	43	50	77	132	65	50	9.5	10	7.5	4
DN65	2½"	46	66	84	140	65	50	9.5	10	7.5	4
DN80	3"	46	80	96	147	65	50	9.5	10	7.5	4
DN100	4"	52	101	112	172	90	70	11	12	9.5	4
DN125	5"	56	124	121	187	90	70	11	12	9.5	4
DN150	6"	56	150	134	201	90	70	11	12	9.5	4
DN200	8"	60	201	168	229	125	102	17	19	11.5	4
DN250	10"	68	251	202	269	125	102	20	21	11.5	4
DN300	12"	78	301	234	298	125	102	20	21	11.5	4
DN350	14"	78	340	275	330	175	140	24	24	17.5	4
DN400	16"	102	391	303	358	175	140	36	38	17.5	4
DN450	18"	114	442	356	403	175	140	36	38	17.5	4
DN500	20"	127	486	382	435	210	165	46	48	21.5	4
DN600	24"	154	585	440	510	210	165	55	57	21.5	4
DN700	28"	165	680	490	560	300	254	55	57	17.5	8
DN750	30"	165	699	540	615	300	254	55	57	17.5	8
DN900	36"	200	850	630	705	300	254	55	57	17.5	8



\*All dimensions are in mm unless and otherwise specified.

## TORQUE TABLE

SIZE (mm)	LINE PRESSURE	
	10 BAR	16 BAR
32	5	7
40	6	8
50	7	9
65	15	18
80	18	24
100	25	37
125	45	59
150	110	125
200	140	200
250	200	240
300	280	360
350	610	700
400	750	850
450	860	1500
500	2255	3690
600	3000	3840
700	3600	6500
750	4000	7250
900	4200	7600

## Cv VALUE CHART FOR "VTM" BUTTERFLY VALVES

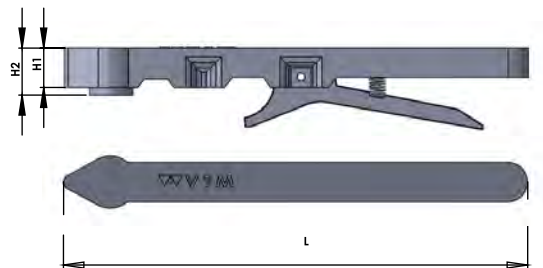
INCH	MM	10°	20°	30°	40°	50°	60°	70°	80°	90°
1 1/2"	40	0.7	3	6	14	20	38	53	62	73
2"	50	0.2	5	9	17	27	53	70	115	145
2 1/2"	65	0.4	8	15	26	42	83	105	175	240
3"	80	0.6	12	22	38	63	125	160	260	440
4"	100	0.8	17	42	73	120	235	305	510	720
5"	125	2	45	88	155	250	490	625	1000	1175
6"	150	3	89	145	250	410	800	1030	1650	2040
8"	200	4	148	250	420	700	1300	1750	2725	3472
10"	250	5	232	390	670	1150	2150	2750	4300	5950
12"	300	6	342	550	1000	1600	3100	4050	5000	8402
14"	350	6	338	715	1549	2761	4568	7230	10844	11917
16"	400	8	464	983	2130	3797	6282	9942	14913	16388
18"	450	11	615	1302	2822	5028	8320	13168	19752	21705
20"	500	14	791	1674	3628	6465	10698	16931	25396	27908
24"	600	22	1222	2587	5605	9989	16528	26157	39236	43116

- NOTE:
- All Torque values are in Nm.
  - All Actuator are selected on basis by adding 30% factor of safety in the torque value required to operate.
  - For Powdery/Non Lubricant media, torque values shall increase by 25%
  - For Dry Gases/Viscous media, torque shall increase by 20%

## ACTUATORS & ACCESSORIES

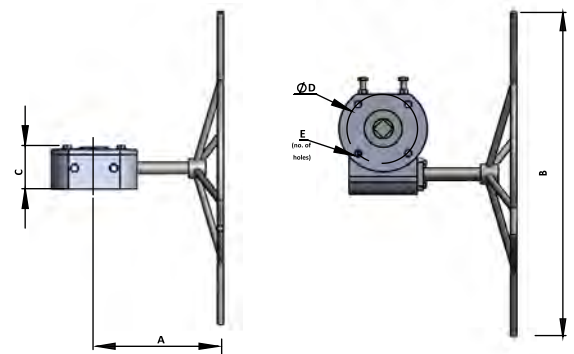
### HAND LEVER

SIZE	L	H1	H2
32/40/50/65/80MM	240.00	25.00	31.00
100/125/150MM	290.00	25.00	31.00
200MM	340.00	28.00	33.00
250/300MM	550.00	32.00	35.00



### GEAR BOX SIZES

SIZE	RATIO	TURN TO CLOSE 90°	MAX. OUTPUT TORQUE (NM)	A	B	C	D	E
32 TO 150mm (1 1/4" - 6")	25:1	6.25	125	145	200	60	50 or 70	4
200 TO 300mm (8" - 12")	32:1	8.00	500	240	300	75	102	4
350 TO 450mm (14" - 18")	47:1	11.75	2000	255	400	85	140	4
500 TO 600mm (20" - 24")	45:1	11.25	4000	290	600	122	165	4
700 TO 900mm (28" - 36")	52:1	13.00	8000	250	800	152	254	8



NOTE: VTM Designed Electric & Pneumatic Actuators are available on Demand.

## CHEMICAL RESISTANCE GUIDE

FLUID / MATERIAL	DISC			SEAT		
	AL-BRZ	DUCTILE	304/316	NBR	EPDM	VITON
Acetic Acid (10%)	Very Poor	Poor	Excellent	Very Poor	Good	Very Poor
Air	Excellent	Excellent	Excellent	Excellent	Excellent	Excellent
Ammonia (anhydrous liquid)	Very Poor	Good	Excellent	Poor	Good	Very Poor
Ammonia (soluton)	Very Poor	Good	Excellent	Good	Good	Very Poor
Ammonium Sulfate	Very Poor	Poor	Good	Excellent	Excellent	Good
Animal Oil	Good	Excellent	Excellent	Excellent	Good	Good
Calcium Carbonate	Very Poor	Very Poor	Good	Excellent	Excellent	Excellent
Carbonic Acid	--	Very Poor	Good	Good	Good	Excellent
Chlorinated Water	Very Poor	--	Poor	Good	--	Excellent
Ethane	--	Good	Good	Excellent	Very Poor	Excellent
Ethyl Alcohol	Good	Good	Excellent	Good	Excellent	Good
Freon12	Excellent	Good	Excellent	Good	Excellent	Poor
Gasoline (refined/unleaded)	Good	Good	Excellent	Poor	Very Poor	Excellent
Hydrochloric Acid	Very Poor	Very Poor	Very Poor	Poor	Good	Excellent
Hydrogen Gas (cold)	Excellent	Good	Excellent	Good	Good	Excellent
Lubricatng Oil (petroleum base)	Good	Excellent	Excellent	Excellent	Very Poor	Excellent
Methyl Alcohol	Excellent	Good	Excellent	Good	Excellent	Poor
Mineral Oil	Good	Good	Excellent	Excellent	Very Poor	Excellent
Natural Gas	Excellent	Excellent	Excellent	Good	Very Poor	Excellent
Oxygen (cold)	Excellent	Good	Excellent	Good	Good	Excellent
Petroleum Oil (refined)	Good	--	--	Good	Very Poor	Good
Propane Gas	--	Good	Excellent	Excellent	Very Poor	Excellent
Sea Water	Excellent	Very Poor	Good	Excellent	Excellent	Excellent
Soybean Oil	--	Poor	Excellent	Excellent	Poor	Excellent
Sulfuric Acid (7%)	Very Poor	Very Poor	Good	Good	Good	Excellent
Sulfuric Acid (20%)	Very Poor	Very Poor	Very Poor	Very Poor	Good	Excellent
Sulfuric Acid (50% & larger)	Very Poor	Very Poor	Very Poor	Very Poor	Good	Good
Sulfurous Acid	Very Poor	Very Poor	Good	Poor	Poor	Excellent
Steam (100°C)	Excellent	Excellent	Excellent	Very Poor	Good	Poor
Vegetable Oil	Good	Poor	Excellent	Excellent	Poor	Excellent
Water (hot, 150°F)	Excellent	Poor	Excellent	Very Poor	Good	Excellent

The above performance data has been developed from field testing, customer field reports and/or in-house testing. Properties/applications shown are typical. Your specific application should not be undertaken without independent study and evaluation for suitability. While the utmost care has been used in compiling this data, we assume no responsibility for errors

### VALVE PRESSURE RATING

RATING	SHELL(Kg/cm <sup>2</sup> )	SEAT(Kg/cm <sup>2</sup> )
<b>PN-10</b>	15.0	11.0
<b>PN-16</b>	24.0	17.6
<b>PN-25</b>	38	28

## V.A. VALVES

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Due to continuous development program, design and data in this leaflet are subject to change without prior notice.

### GUARANTEE

All valves are guaranteed against any manufacturing defects for a period of 12 months from date of supply, provided the valves have not been misused, damaged or installed for services they are not recommended. The company shall be liable to furnish part / parts thereof or full valve as the company may deem fit.

Authorized Stockist

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PIONEERING FLUID CONTROLS

[www.vtm-valves.com](http://www.vtm-valves.com)



Instruction Manual for Electric Actuator



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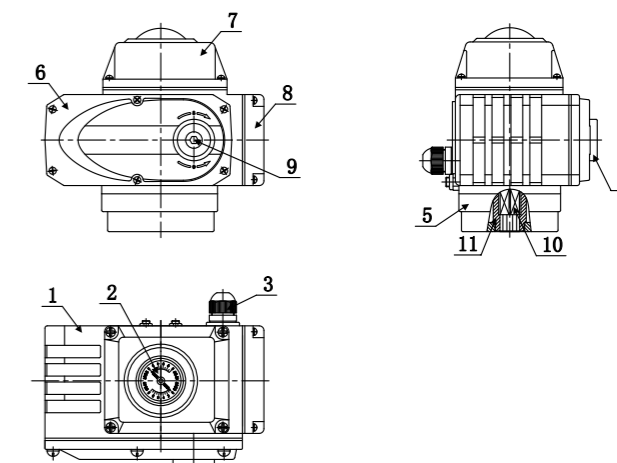
## Product Introduction

The Electric Actuator is distinguished by its special design, beautiful appearance, great performance and long-time operation. The rotary valve electric actuator will win customers' hearts by its supreme performance.

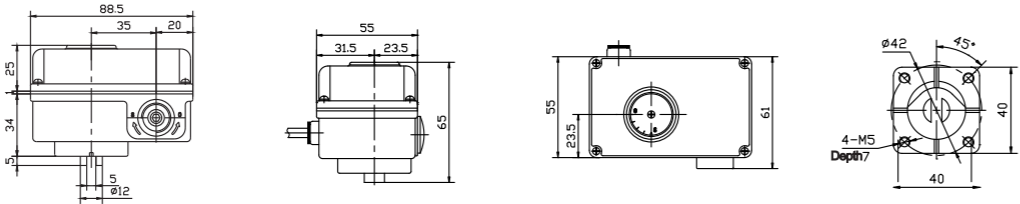
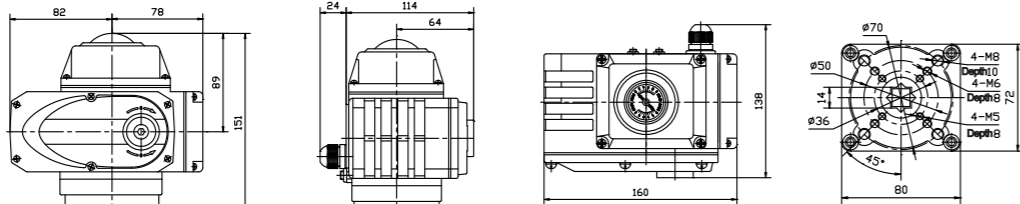
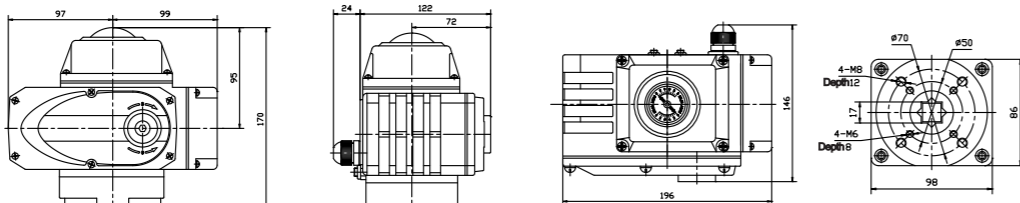
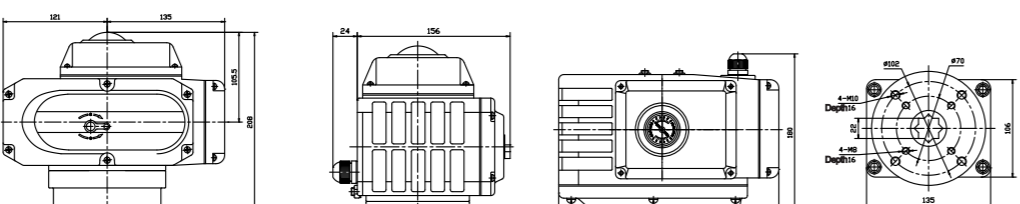
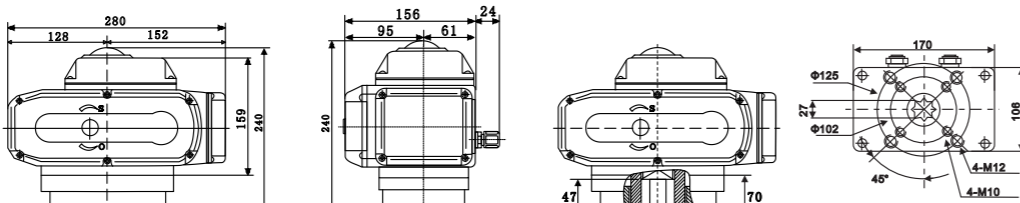
- ◆Powerful function: Modulating, proportional, on-off, and various output signal;h
- ◆Small Size: 35% smaller than other of the same kind;
- ◆Light Weight: 35% lighter than other of the same kind ;
- ◆Beautiful Appearance: Die-casting aluminium alloy cover can prevent disturbance of electromagnetic;
- ◆Precision and Wear-resistance: Integration of worm wheel and output axle avoids the separation among keys and the forged brass alloy material is featured by high strength and good wear-resistance;
- ◆Safety Guarantee: Tested by AC 1500V and can withstand it; F-grade insulation motor guarantees safe operation;
- ◆Easy to Form Complete Set: 110V, 220V, 380V alternate current and direct current are all available for simple connection;
- ◆Easy Application: No oil or point inspection is needed; waterproof, antirust and optional installation angle;
- ◆Protection Appliance: Double limits, over-hot protection, overload protection;
- ◆Various Motion Time: 9s, 13s, 15s, 30s, 50s, 100s (Set Before Delivery);
- ◆Antirust and Anti-corrosion: Whole machine support, coupler and screws are made of stainless steel;
- ◆Intelligent Numerical Control: Intelligently control module is built in the actuator body so that there is no need to mount positioner. Digit setting and adjusting, highly accuration and self-diagnosis can be realized.

## Appearance and Parts Name

1	Case Body
2	Opening Mete
3	Inlet Wire Lock
4	Rubber Cover of Handle Shaft
5	No-Bracket Installation
6	Gear Box Cover
7	Electric Cover
8	Wiring Cover
9	Handle Shaft Cover
10	Output Shaft
11	Adapter



### Overall Dimension

I-02	
I-05	
I-10	
I-20/40/60	
I-100/200	

### I-02 Performance Parameter

Model	I-02
Power Supply(V)	AC85-260
Output Torque(N.m.)	6
Motion Scope(°)	0-90
Motion Time(S)	7 (second)
Rated Current(A)	0.2
Drive Motor(W)	4.6
Protection Device	Motor Protection Thermistor, Mechanical Limit Block at Both Open and Close Side
Opening Detection	Position Detection Components for Full Open and Close: a. Full Open: Red(LED) b. Full Close: Green(LED)
Output Signal	Output Signals for Full Open and Close (NPN Transistor, Collector Current, Emission Stage) (Connection Capacity:DC50V,20mA)
Application Environment	Temp:25°C ~ +55°C Humidity: 10-90%RH
Output Shaft	SUS303, Φ:12, Pit:5, Depth:5
Handle Shaft	Hexagon Hole Opposite Angle : 4mm(With Lid)
Waterproof	JIS C0920 Grade 6 ( IP 65)
Install direction	360-Degree Optional Direction
Distribution Cable	0.3×6 Core Cable 30cm
Body Material	Die-Casting Aluminium Alloy
Colour of Coating	Gray and White
Weight(kg)	0.5

### I-05 Performance Parameter

Model	I-05				
Power Supply(V)	DC24	AC24	AC110	AC220	AC380
Output Toque(Nm)	50				
Motion Times(S)	7	20			
Rotary Angle (°)	0~360				
Motor Power(W)	10	15			
Rated Current(A)	0.5	2.2	0.48	0.24	0.15
Weight(kg)	2.3	2.7			
Insulation Resistance (MΩ)	DC24V: 100/250VDC AC110/220V/380V: 100/500VDC				
Voltage Resistance Class	DC24V: 500VAC, AC110/220V: 1500VAC, AC380V: 1800VAC. (1 Min.)				
Protection Class	IP68				
Installation Position	Optional Direction: 360°				
Electrical Connection	M18×1.5 Water-proof Cable Connectors, Electric Power Wire, Signal Wire				
Ambient Temp.	-30°C ~ +60°C				
Circuit Control	B, S, K, R, A, D, H, T				
Optional Function	I. Over Torque Protectors II. Dehumidify Heater				

### I-10 Performance Parameter

Model	I-10				
Power Supply(V)	DC24	AC24	AC110	AC220	AC380
Output Toque(Nm)	100				
Motion Time(S)	10	30			
Rotary Angle (°)	0~360				
Motor Power(W)	20	25			
Rated Current(A)	0.85	3	0.7	0.32	0.2
Weight(kg)	4	4.3			
Insulation Resistance (MΩ)	DC24V: 100/250VDC AC110/220V/380V: 100/500VDC				
Voltage Resistance	DC24V: 500VAC, AC110/220V: 1500VAC, AC380V: 1800VAC.( 1Min.)				
Protection Level	IP68				
Installation Position	360-Degree Optional Direction				
Electriad connection	M181.5 Water-proof Cable Connector, Electric Power Wire, Signal Wire				
Ambient Temp.	-30°C ~ +60°C				
Circuit Control	B, S, K, R, TA, D, H				
Optional Function	I. Over Torque Protectors II. Dehumidify Heater				

### I-20/40/60 Performance Parameter

Model	I-20					I-40					I-60				
Power Supply(V)	DC24	AC24	AC110	AC220	AC380	DC24	AC24	AC110	AC220	AC380	DC24	AC24	AC110	AC220	AC380
Output Toque(Nm)	200					400					600				
Motion Time(S)	12	30/60				15	30/60				20	45/60			
Rotary Angle (°)	0~90					0~90					0~90				
Motor Power(W)	40					70	90				90				
Rated Current(A)	1.2	7.5	1.6	0.88	0.4	2.5	9	2.2	1	0.48	2.5	9	2.2	1	0.5
Weight(kg)	8.7	9.3				8.8	10				8.8	10			
Insulation Resistance (MΩ)	DC24V: 100/250VDC AC110/220V/380V: 100/500VDC														
Voltage Resistance	DC24V: 500VAC AC110/220V: 1500VAC AC380V: 1800VAC. ( 1Minute)														
Protection Class	IP68														
Installation Position	360-Degree Optional Direction														
Electrical Connection	M181.5 Water-proof Cable Connectors, Electric Power Wire, Signal Wire														
Ambient Temp.	-30°C ~ +60°C														
Circuit Control	B, S, K, R, A, D, H, T														
Optional Function	I. Over Torque Protectors II. Dehumidify Heater														

### Performance Parameter of I -100/200 Series

Performance	Model	I-100				I-200			
	Power(V)	AC24	AC110	AC220	AC380	AC24	AC110	AC220	AC380
Motor Power(W)		100				100			
Rated Current(A)		9	2.2	1.2	0.48	9	2.2	1.2	0.48
Output Torque(Nm)		800/1000				2000			
Motion Time (S)		30/50				100			
Circuit Control		B, S, K, R, A, D, H, T							
Rotary Angle (°)		0~90							
Weight(kg)		11.2				11.8			
Voltage Resistance		AC110V/AC220V:1500VAC , AC380V:1800VAC(Minute)							
Insulation Resistance(MΩ)		100MΩ/500VDC							
Protection Class		IP-68							
Ambient Temp.		-30°C ~ +60°C							
Installation Angle		360-Degree Optional Direction							
Case Body Material		Die-Casting Aluminium Alloy							
Optional Function		I. Over Torque Protectors II. Dehumidify Heater							



### Performance Parameter of Modulating Type

Model	IM-05A	IM-10A	IM-20A	KST-40A	IM-60A	IM-100A	IM-200A
	Power	DC24V/AC24V, AC110V, AC220V, AC380V, 50/60HZ					
Performance							
Motor Power (W)	15W	25W	40W	90W	90W	100W	100W
Rated Current (A)	0.24A (AC220V)	0.32A (AC220V)	0.88A (AC220V)	1A (AC220V)	1A (AC220V)	1.2A (AC220V)	1.2A (AC220V)
Output Torque (N.m.)	50Nm	100 Nm	200 Nm	400 Nm	600 Nm	1000 Nm	2000 Nm
Motion Time (S)	20S	30S	30S	30S	45S	50S	100S
Rotary Angle (°)	0~360°			0~90°			
Input Signal	4~20mA.DC、1~5V.DC、0~10V.DC ( Others could be set before delivery )						
Output Signal	4~20mA.DC ( Others could be set before delivery )						
Precision Grade	1%						
Weight	2.7kg	4.3kg	9.3kg	10kg	10kg	11.2kg	11.8kg
Voltage Resistance	DC24V:500VAC/1min			1500VAC/1min			
Insulation Resistance	DC24V:100MΩ/300VDC			100MΩ/500VDC			
Protection Class	IP-68						
Ambient Temp.	-30°C ~ +60°C						
Installation Angle	360-Degree Optional Direction						
Case Body Material	Die-Casting Aluminium Alloy						
Optional Function	I. Over Torque Protectors II. Dehumidify Heater						

### Wiring Diagram

Open Switch and Close Switch are strictly prohibited to be connected at the same time.

**Z : 02 On-Off Type**

The actuator is equipped with dedicated cable (30cm) to distribute wiring for power and full closed & full open output signal ( NPN Transistor & Collector Current ).

**Wiring Instructions:**

1. Wiring distribution shall be conducted by qualified electrical engineer in accordance with electrical equipment technical standard.
2. It's prohibited to conduct wiring distribution when it's raining or the air is highly humid.
3. Make sure the wiring diagram is correctly connected.
4. Dedicated cable is built in the actuator so that internal wiring is not needed.
5. Top cover is strictly forbidden. (Cable is already available)
6. It's strictly forbidden to connect Open Switch and Close Switch simultaneously when the power is on.

**B: On-Off Type (Standard)**

Valve can be controlled to open and close by the on-off circuit and the circuit will output a group of active position signal to indicate the valve is in full close or full open position.

**Wiring Instruction:**

1. Connect terminal 1 with null line.
2. When terminal 2 connects with phase line, it indicates "Opening" is in operation.
3. When terminal 3 connects with phase line, it indicates "Closing" is in operation.
4. When "Opening finishes its operation, the signal lamp connected with terminal 4 will be on.
5. When "Closing finishes its operation, the signal lamp connected with terminal 5 will be on.

**S: Passive Contact Type**

Valve can be controlled to open and close by the on-off circuit and the circuit will output a group of passive position signal to indicate the valve is in full close or full open position.

**Wiring Instruction:**

1. Connect terminal 1 with null line.
2. When terminal 2 connects with phase line, it indicates "Opening" is in operation.
3. When terminal 3 connects with phase line, it indicates "Closing" is in operation.
4. Terminal 4 is the passive contact common port.
5. When "Opening finishes its operation, terminal 5 will output Fully Open Signal.
6. When "Closing finishes its operation, terminal 5 will output Fully Close Signal.

**K: With Position Generator Type**

Valve can be controlled to open and close by the on-off circuit and the circuit will output current signal corresponding to the openness angle of valve.

**Wiring Instruction:**

1. "N" is null line and "L" is phase line.
2. When "L" is connected with "On", valve is in open operation.
3. When "L" is connected with "Off", Valve is in close operation.
4. Connect "+" of output terminal with the positive pole of output signal and "-" with negative pole of output signal.

**R: Opening Signal Type**

Valve can be controlled to open and close by the on-off circuit and the circuit will output resistant signal corresponding to the openness angle of valve.

**Wiring Instruction:**

1. Terminal 1 connect with null line. Terminal 5 is the lift arm of potentiometer.
2. When terminal 2 connects with phase line, valve will open; when terminal 3 connects with phase line, valve will close.
3. Terminal 4 is the low side of potentiometer. When valve opens, the resistance between terminal 4 and 5 will increase with the opening degree.
4. Terminal 6 is the high side of potentiometer. When valve close, the resistance between terminal 4 and 5 will increase with the closing degree.

## Wiring Diagram

<p><b>A: Modulating Type</b></p>	<p><b>A: Modulating Type</b></p> <p>The opening or closing is realized by the standard signal through external computer or industry meter. Meanwhile, the corresponding standard signals will be output.</p> <p><b>Wiring Instrument:</b></p> <ol style="list-style-type: none"> <li>1. Connect "N" of input terminal with null line and "L" with phase line.</li> <li>2. Connect the "+" of external control terminal with positive pole of input signal, "-" with negative pole of input signal.</li> <li>3. Connect the "+" of feedback terminal with positive pole of input signal, "-" with negative pole of input signal.</li> </ol>
<p><b>D: Direct Current On-Off Type</b></p>	<p><b>D: Direct Current On-Off Type</b></p> <p>Opening or closing operation of valve can be realized by switching the positive and negative pole of external direct current. Meanwhile, a group of passive contact signal will be output to indicate fully openness or close of valve.</p> <p><b>Wiring Instrument:</b></p> <ol style="list-style-type: none"> <li>1. Valve will open when terminal 1 is connected with positive pole and terminal 2 with negative pole.</li> <li>2. Valve will close when terminal 1 is connected with negative pole and terminal 2 with positive pole.</li> <li>3. Terminal 4 is the passive contact common end.</li> <li>4. When "Opening finishes its operation, terminal 5 will output Fully Open Signal.</li> <li>5. When "Closing finishes its operation, terminal 6 will output Fully Close Signal</li> </ol>
<p><b>H: Three-Phase On-Off Type</b></p>	<p><b>H: Three-Phase On-Off Type</b></p> <p>Valve can be controlled to open and close by the on-off circuit and the circuit will output a group of active position signal to indicate the valve is in full close or full open position.</p> <p><b>Wiring Instruction:</b></p> <ol style="list-style-type: none"> <li>1. Connect terminal 1, 2, 3 with 3-phase alternate current. The motor will be operated to rotate clockwise and anticlockwise through external phase inverter circuit.</li> <li>2. Terminal 4 is the common port of external control circuit.</li> <li>3. Terminal 5 is "open" operation control.</li> <li>4. Terminal 6 is "close" operation control.</li> <li>5. When "Opening finishes its operation, terminal 7 will output Fully Open Signal.</li> <li>6. When "Closing finishes its operation, terminal 8 will output Fully Close Signal.</li> </ol>
<p><b>T: Three-Phase Passive Contact Type</b></p>	<p><b>T: Three-Phase Passive Contact Type</b></p> <p>Valve can be controlled to open and close by the on-off circuit and the circuit will output a group of active position signal to indicate the valve is in full close or full open position.</p> <p><b>Wiring Instruction:</b></p> <ol style="list-style-type: none"> <li>1. Terminal 1, 2, 3 connected with 3-phase power. By means of the external phase reversing circuit, running normally or reversibly of motor.</li> <li>2. Terminal 4 is the common port of external control circuit.</li> <li>3. Terminal 5 is "open" operation control.</li> <li>4. Terminal 6 is "close" operation control.</li> <li>5. Terminal 7 is passive contact common port.</li> <li>6. When "Opening finishes its operation, terminal 8 will output Fully Open Signal.</li> <li>7. When "Closing finishes its operation, terminal 9 will output Fully Close Signal.</li> </ol>

## Power, Voltage

Please choose power voltage according to product nameplate or wiring diagram. Available voltages are listed as followings: AC380V±10% 50/60HZ; AC220V±10% 50/60HZ; DC24V

\*Notes: When choosing AC380V, pay attention to the sequence of phase line during wiring and make sure travel switch can correctly control openness and close of valve. Otherwise, the actuator would be damaged.

### Selection of Fuse and Circuit Breaker:

In order to protect the actuator, avoid short circuit and reduce injuries, A circuit breaker can be connected at the power input terminal of each actuator. Choose the appropriate fuse protection based on the following table.

Model	Voltage				
	AC380V	AC220V	AC110V	AC24V	DC24V
I-05	2A	2A	3A	5A	5A
I-10	2A	3A	5A	7A	7A
I-20/40/60	3A/5A	5A/7A	7A/10A	10A/11A	15A
I-100/200	5A	7A	10A	20A	

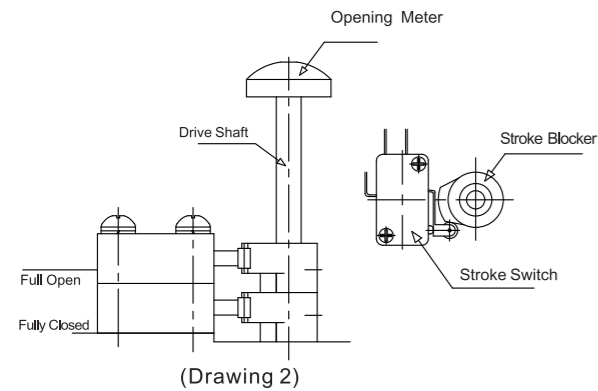
Power lines of two or several electric devices can't be connected in parallel;  
Several electric devices can't be controlled by the same connection point; Otherwise, you will lose control or the motor will be overheating.

## Installation

### Cautions for Indoor Installation

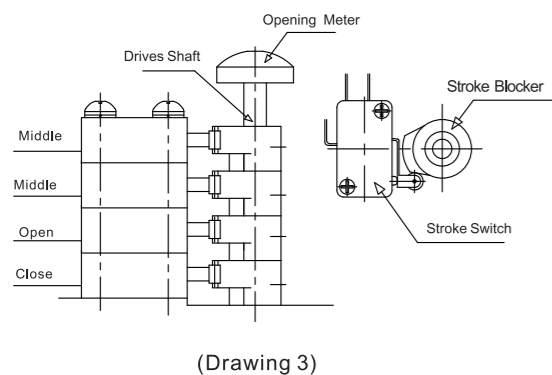
- ◆Products can't be installed in the room with explosive air unless they are of anti-explosive;
- ◆Please install a shield to cover the product for safety if the product is installed in a place with water or raw material;
- ◆Space is needed for inlet wiring or manual operation.

## Adjustment of On-Off Type



### Adjustment of Limit Position Switch(Drawing2)

- ◆ Close the valve to fully closed position.
- ◆ Loosen the fastening screw of stroke blocker, turn the blocker below to activate the stroke switch. "Click" sound will be heard when the switch moves. Then fasten the screw. Adjustment way of full open position is the same as above.



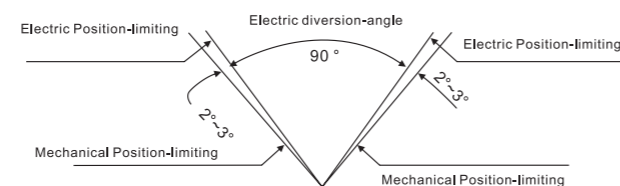
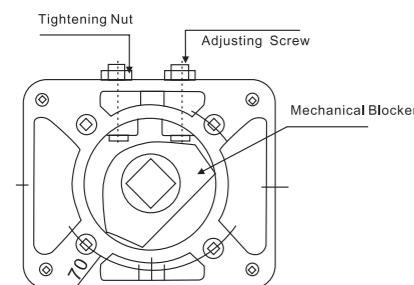
### Adjustment of Middle Position Switch ( Drawing 3)

- ◆ Operate the valve manually to desired position.
- ◆ Loosen the fastening screw of stroke blocker, turn the blocker below to activate the stroke switch. "Click" sound will be heard when the switch moves. Then fasten the screw. Adjustment way of full open position is the same as above.
- ◆ Motion position of two middle position switch can be adjusted in accordance with requirement.

## Regulation of Mechanical Position-limiting (Drawing 4)

- ◆ Rotate the handle to fully open position.
- ◆ Loosen tightening nut and rotate to adjust screw in order to make it contact the mechanical blocker. Then, rotate screw semi-circle and fasten the nut. In anticlockwise direction for tightening nut.
- ◆ Using same method, operator could regulate mechanical link-stopper at wholly-closed position.

\* Notes: Mechanical position limit must lag behind the electric position limit. Or the motor will be too hot.



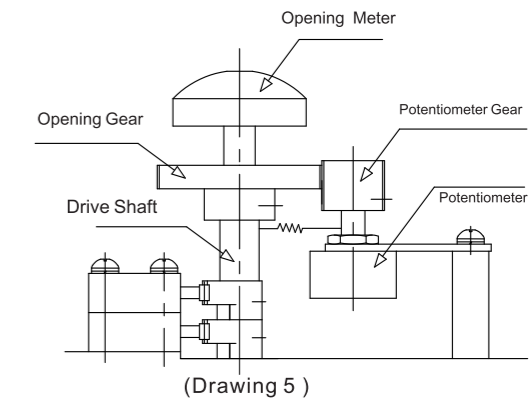
( Drawing 4 )

## Potentiometer Adjustment (Opening Type R, Modulating Type A) (Drawing 5)

- ◆The resistance value of potentiometer is 1KΩ , 5KΩ ;
- ◆Rotate valve to fully closed position with handle;
- ◆Loosen screw of opening-gear and rotate opening gear for regulating potentiometer. Measure resistance value between 4 and 5 wiring terminals by universal meter, and make the resistance value achieve 10Ω, tighten opening gear, fixing screw. (If it is modulating type, resistance between RV and RS jacks shall be measured when connecting the seven-line connector).

\*Notes: Potentiometer can be loosen for adjustment.

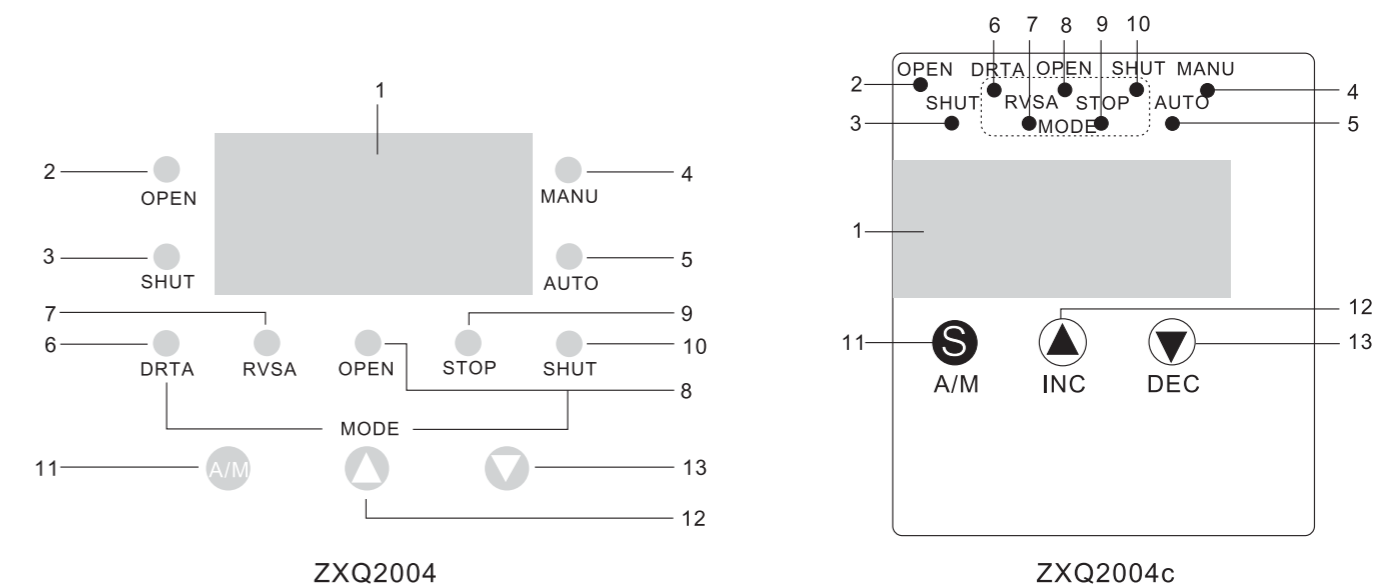
When fixing, pay attention to the mesh between potentiometer gear and opening gear, which can't be too large or small, or else, it would directly affect the precision of actuator.



## Adjustment of Modulating Type

### Actuator Adjustment

- ◆Before adjustment, you should understand the adjustment method of open and close angle. Adjust electric position-limiting, potentiometer and mechanical position-limiting of actuator in accordance with the fully openness and close of valve.



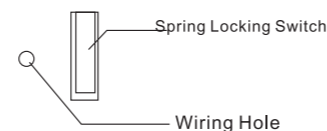
## Positioner Panel

Data Display	1	LED Window	Actual opening value, setting opening value, temperature inside positioner and setting parameter can be indicated by switching the buttons.
Status Indication	2	OPEN	Output control "open", relay will shut
	3	SHUT	Output control "closed", relay will shut
	4	MANU	Manual Status
	5	AUTO	Automation Status
Mode Indication	6	DRTA	Obverse-action mode, corresponding output of input signal is stated as following: 4mA-full(Normally set as fully open); 20mA-zero(Normally set as fully closed)
	7	RVSA	Reverse-action mode, corresponding output of input signal is stated as following: 4mA-zero (Normally set as fully closed); 20mA-full (Normally set as fully open)
	8	OPEN	Input signal suspension indicates "open", actuator opens to the largest position limit.
	9	STOP	Input signal suspension indicates "stop", actuator remains in the current position.
	10	SHUT	Input signal suspension indicates "closed", actuator closes to the largest position limit.
Button	11	A/M	Manual/Automatic switching button, button for parameter input, modification and switch
	12	▲	Value Increasing Button. It can be used to switch and indicate the set openness value in automatic status. It shows "open" in manual status.
	13	▼	Value Decreasing Button. It can be used to switch and indicate the inside temperature of positioner in automatic status. It shows "closed" in manual status.

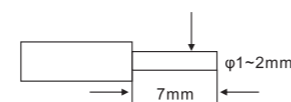
## Wiring Introduction

ZXQ2004 intelligent positioner can be connected with electric actuator through one seven-line connector:

There is a group wiring tightened by six-line spring pressure on positioner(as shown in drawing 6), of which the N, L lines is connected with mid-line and phase-line of 220VAC single-phase circuit, two 4~20mA(or 1~5V) IN terminals is connected with control current (voltage), two 4~20mA terminals are to give feedback of current signal output, which can be connected with ammeter so as to display actual opening value of valve, it also can be not connected.  $\Phi 1\sim 2\text{mm}$  single-core or multi-core infrared insulated line (shown in diagram 7) can be adopted as connection line. It is suggested to fasten tightly and plate tin onto multi-core line if this line is adopted. It is suggested to insert single-core line or tin-plated multi-core line into the hole if there is spring resistance, insert another 4-5 mm. If the wire is soft, insert the wire into the hole and press the spring locking switch with straight screwdriver, insert another 4-5mm and loosen the switch, then the wire is locked. The wire can't be pulled out under normal circumstance. If it's needed to pull out the wire, press the switch beside the corresponding hole with screwdriver and then pull out the wire.



( Drawing 6 )

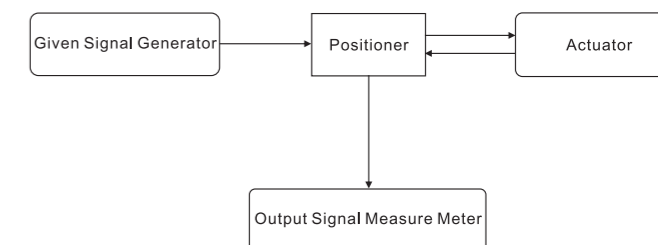


( Drawing 7 )

## Setting Operation Intelligent Positioner

Connect the lines between given signal source, output signal measure meter (Disconnection is also allowed) and power supply according to wiring drawing.

- ◆When the power is on, the actual opening value of valve would be displayed, and the positioner is under auto test status at this time.
- ◆Press A/M button to switch to manual state, press ▲and▼ buttons separately to manually control the "open" and "close" of actuator.
- ◆Under automatic status, press ▲to check the set openness value of valve and the varying trend & stability of input signal.
- ◆Under automatic status, press ?to observe the inside temperature of positioner. When it exceeds 70 centigrade, the positioner will cease the open and close control of actuator;
- ◆Under automatic status, press A/M button for 4S to enter the setting parameter shown in the table below, the parameter value could be revised by pressing▲and ▼, see the operation progress diagram for details.



## Setting Operation Intelligent Positioner

### Parameter List

Parameter	Indicated Value	Meaning	Set Value
U0	00x.0	X=1 Electronic braking is allowed, X=0 Electronic braking is not allowed	1
	000.x	X=0 Positioning accuracy is not allowed but time readjustment is allowed. X=1,2,3 Time readjustment is not allowed but positioning accuracy is allowed	0
U1	00x.0	Set positive and active action. X=0 is positive, x=1 is negative.	1
	000.x	Signal Suspension Mode, x=0(neglection) x=1(open) x=2(stop) x=3(shut)	2
U2	xxx.x	Control output lower limit value is $0\leq U2 < 100$ , manual zero and full setting will not be limited by the parameter	0.0
U3	xxx.x	Control output upper limit value is $0\leq U2 < 100$ , manual zero and full setting will not be limited by the parameter	100.0
U4	00x.x	The precision is adjustable, it equals $x.x/100$	0.4
U5	xxx.x	Operation password, (U5=003.1 is opening setting of entering the actuator )	
U6	xxx.x	Actuator zero position confirmation, press ▲and ?button. When it reaches full position, press A/M button for zero position confirmation, then enter U7.	
U7	xxx.x	Actuator zero confirmation. Press ▲and ?button. When it reaches full position, press A/M button for full position confirmation.	

Notes: Other parameters are reserved by manufacturer, Appendix will be taken for reference if needed.

✘The parameters of actuator have been set before delivery. It can be applied by directly connecting power supply, signal source and output signal measure meter (Disconnection is also allowed) without any resetting. If it's needed to set, the following procedure could be followed.

◆Set the zero and full position of actuator. This setting will exert no effect on input, outputting signal of positioner. After the resetting, rotary angle shall be reset, then the actuator could work normally. The setting falls into the following two methods:

Method 1 (Manual Setting) (According to the operating process):

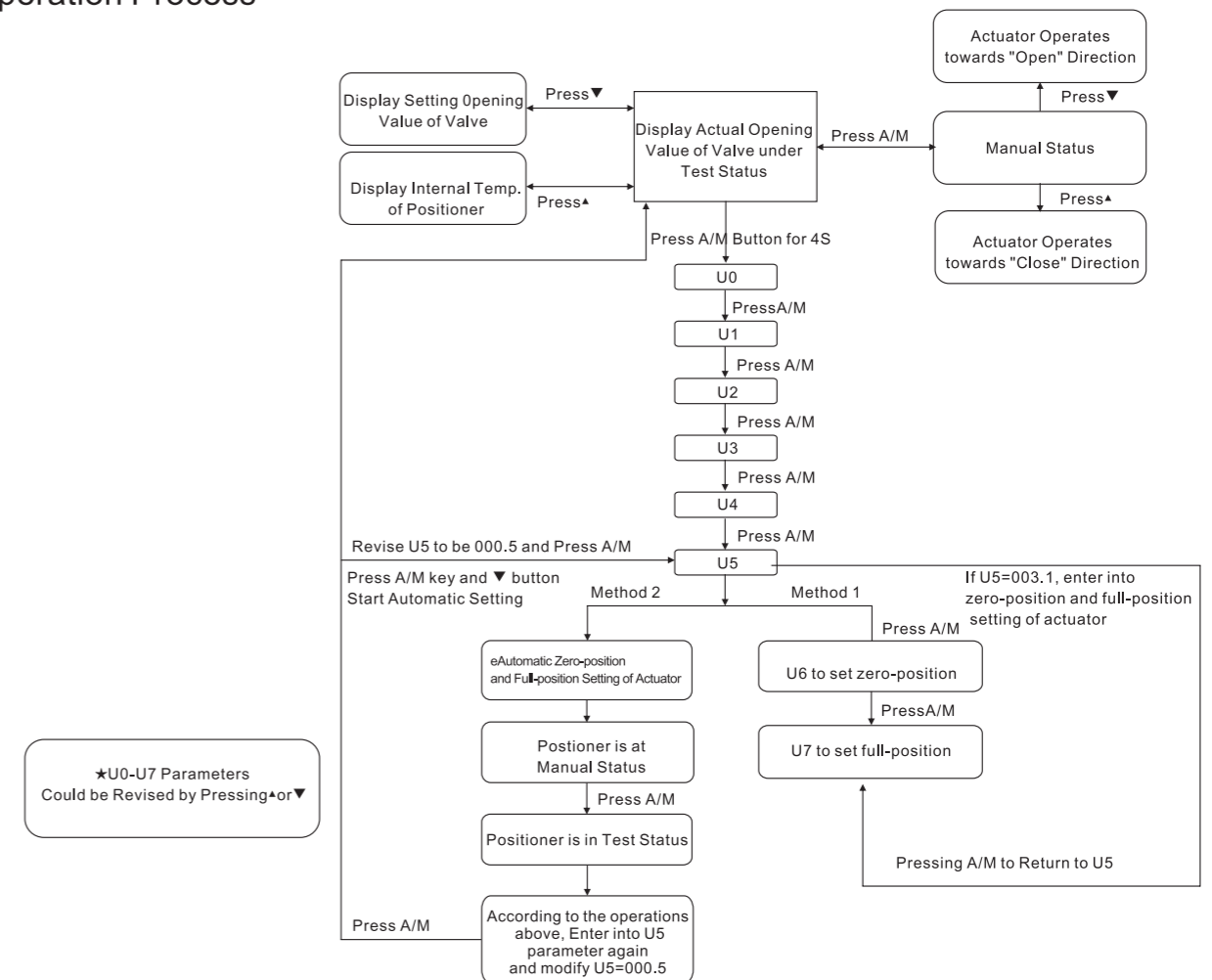
- ◆Enter into U5 and modify U5= 003. 1, then press A/M button again and enter into U6 parameter (set zero position). Press▲and▼ button, the actuator will operate towards "open" and "close" direction accordingly. The actual opening value of valve displayed will increase and decrease accordingly. When expected zero position (usually set at full close position) is reached, press A/M button for zero position confirmation and enter into U7 parameter.
- ◆Enter into U7 parameter (set full position), press▲ and▼ button to expected full-position(normally y at full open position ),and press A/M button for full position conformation, The actuator will be back to 90% position automatically and return to U5, then return to U5.
- ◆Revise U5=000.5 to return to test control status.

Method 2 (Automatic Setting)

- ◆Enter into U5 and revise U5 to be 003. 1, then press A/M button and ▼ button and then release them at the same time. Automatic setting will be started. The zero position will first be set in positioner and then the full position. The positioner will be in manual status after setting. ★Re-enter parameter U5 and modify U5=000.5 (default value) and then press A/M button, the set result Will be saved.

- ◆During test control process of positioner, the actuator will vibrate and be heated because of input signal quality, external electromagnetism disturbance. To avoid the vibration, the U0 (000.X) can be modified:
  1. Set x=0, the position precision will remain the set precision during the vibration of actuator, the readjustment time of actuator will increase to 7 s to meet the requirement of precise positioning and interval operation of actuator;
  2. X=1,2,3, the readjustment time will remain unchanged (about 2s) during vibration of actuator. The precision of actuator will decrease so as to work under the most appropriate precision.
 ✘If there is 10s interval during parameter modification, test control status will be restored.

## Operation Process



## Setting Operation of Intelligent Positioner

### Error Code List

Error Code	Meanings
E-01	Controlling Signal Suspension or below 0.3mA
E-03	Signal Feedback line or open-close line between positioner and actuator are connected wrongly
E-05	Actuator vibrates heavily, maybe because of the instability of input signal or feedback signal, high precision, etc.
E-06	Actuator is blocked during operating towards close direction.
E-07	Actuator is blocked during operating towards open direction.
E-08	Inside temperature of positioner exceeds 70°C

### Cautions for Outdoor Installation

- ◆Please install a shield to cover the product to avoid rain or direct sunlight;
- ◆Space is needed for inlet wiring or manual operation.

\*Notes: The sunlight outdoor would lead to high-temperature which can accelerate aging of components and even losing effectiveness;  
The rain would accelerate aging of rubber-pad. Moreover, failure to avoid rain will lead to damage to product.

### Ambient Temperature and Fluid Temperature Condition

- ◆Ambient temperature shall be between -30°C and +60°C.

Note: Actuator with damp heater shall be chosen when it is applied in place with temperature below zero centigrade or with large temperature gap.

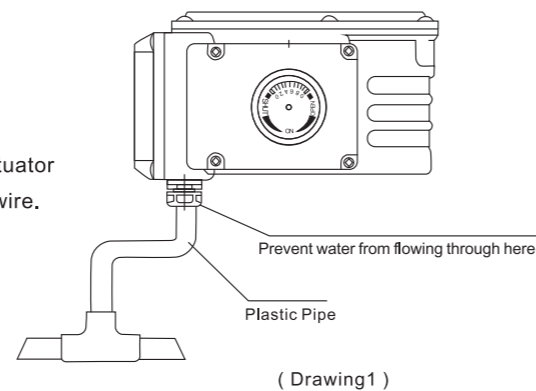
- ◆High-temperature connector shall be used to mount the actuator on valve if the fluid temperature is high.

### Wirng Cable and Wiring

- ◆φ 8 cable shall be applied for I-05 PG11 wire-in line lock.
- ◆φ 8 cable shall be applied for I-10 PG11 wire-in line lock.
- ◆φ 8 cable shall be applied for I-20/40/60/100/200 PG11 wire-in line lock.
- ◆φ 8 cable can be applied according to dimension of wire-in line lock so as to guarantee safety and reliability of wiring;
- ◆Pass the cable through line-lock and fasten line end onto terminal stand;
- ◆Tighten cover of wire-lock for fastening the cable.

### Wiring Line Pipe

- ◆When using line-pipe, it must be waterproof;
- ◆As shown in drawing 1, the actuator shall be higher than line pipe to prevent actuator damage resulted from water drop flowing into the actuator by walking along the wire.

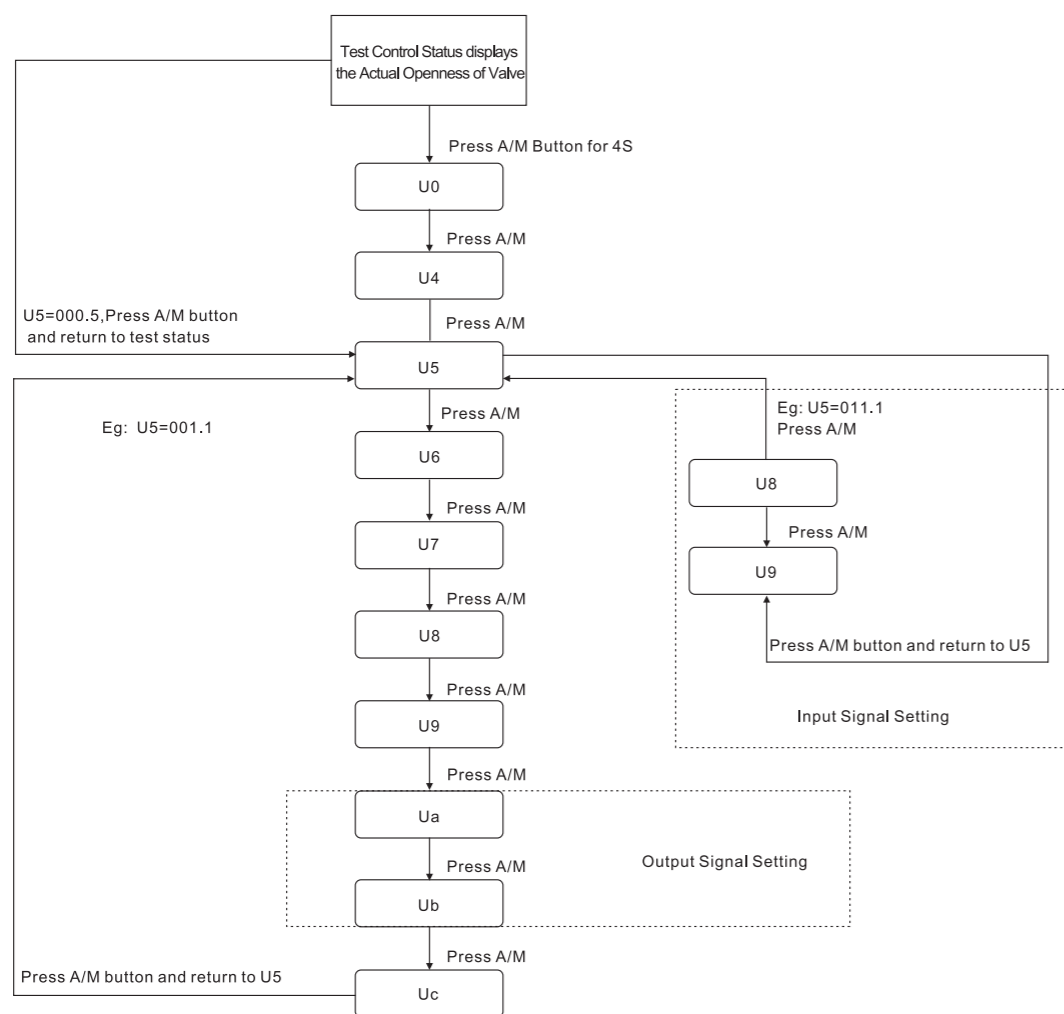


### Model Selection

Model	Output Torque	Motion Time (0 ~ 90°)	Power Supply	Hard -Sealing Butterfly Valve	Soft-Sealing Butterfly Valve	Ball Valve	Ventilating Butterfly Valve
					≤PN1.6MPa	≤PN1.6MPa	≤PN1.0MPa
I-02	6N.M	7S	AC110V, AC220V, 50/60HZ, DC24V		DN25	≤DN20	
I-05	15N.M	10S					
	30N.M	20S			≤DN65	≤DN40	DN50 ~ DN80
	50N.M	30S					
I-10	50N.M	13S					
		15S					
	60N.M	20S		DN40 ~ DN65	DN80 ~ DN125	DN40 ~ DN50	DN100 ~ DN200
I-20	100N.M	30S					
	80N.M	9S					
	100N.M	15S					
	150N.M	20S		DN80 ~ DN125	DN150 ~ DN200	DN65 ~ DN80	DN250 ~ DN300
I-40/60	200N.M	30S					
		60S					
	150N.M	9S					
	250N.M	15S		DN150 ~ DN200	DN250	DN100 ~ DN125	DN350 ~ DN500
I-100	400N.M	20S					
	600N.M	30S					
		60S					
I-200	800N.M	30S		DN250	DN300 ~ DN350	DN150 ~ DN200	DN600 ~ DN800
	1000N.M	50S					
I-200	2000N.M	100S		DN300 ~ DN400	DN400 ~ DN500	DN250 ~ DN300	DN800 ~ DN1000
I-400	4000N.M	100S		DN400 ~ DN500	DN500 ~ DN600	DN300 ~ DN400	DN1000 ~ DN1200
I-600	6000N.M	150S		DN500 ~ DN600	DN800 ~ DN600	DN400 ~ DN500	DN1400 ~ DN1600

Actual torque of valves vary a lot because of different manufacturer and different application even for valves of the samedimension and same model. It is therefore suggested to choose the actuator model by taking 60%-80% of rated output torque of actuator as the working torque of valve.

### Appendix: Other setting --see the drawing below for input signal, output signal setting



### Updating Version Introduction of ZXQ2004 Model

1. A simplified automatic setting method is added. Press A/M button and ?button under automatic status and then release at the same time, the automatic setting will be activated (The function is the same as the automatic setting in method 2)
2. According to the setting method in the instruction manual, set full position(U7), press confirmation button (A/M), it will not return to U5 immediately. However, the electric valve will go to 10% position of setting measurement, then return to U5.
3. Another function of anti-blocking is added to the module. When the electric valve is blocked ( 10% of the full range time), the module will stop controlling output. It will check the blocking again after one minute. If the malfunction does not solved, it will check the valve again three times in one minute. Fault code and valve position value will be shown alternately on the display screen. If the fault still exists, the module ceases checking and displays fault module, then stops working.

The module will be back to normal by pressing the panel button or charging with electricity.

⚠ ( This operation is not required after delivery, please use it under engineer's instruction if needed.)

### Input Signal Setting

- ◆ Under normal test status of positioner, press A/M button for 4s to enter into parameter setting status; the "U0" data value will be displayed. Select "U5" parameter by pressing A/M button, Press ▲ or ▼ button to modify value of "U5" to be 011.1. (See the No. Meaning in the following table for reference)
- ◆ Enter into "U8" parameter value to adjust zero position of input current; When setting, input the zero position through external instrument ( 4mA usually), then press A/M button for confirmation, Then enter into "U9" parameter.

Parameter	Display Value	Meanings
U5	0xx.x	Enter into password setting. U5=011.1, enter into input current setting ; U5=001.1, enter into output current setting; U5=003.1, enter into zero, full position setting of actuator.
U6	xxx.x	Zero-Position Confirmation Parameter of Actuator
U7	xxx.x	Full-Position Confirmation Parameter of Actuator
U8	xxx.x	Zero-Position Parameter Adjustment of Input Current
U9	xxx.x	Full Range Parameter Adjustment of Input Current
Ua	xxx.x	Zero-Position Parameter Setting of Output Current
Ub	xxx.x	Full Range Parameter Setting of Output Current
Uc	xxx.x	Inside Temp. Adjustment

- ◆ "U9" parameter is the full-range adjustment of input current: During adjustment, input the full-range signal (usually 20mA) through external instrument, press A/M button for confirmation, then enter into "U5" parameter to modify U5=000.5, press A/M button for confirmation and exit. The setting will be finished.

### Output Signal Setting

- ◆ Make sure the cleanness and stability of input signal during the operations above.
- ◆ Enter into U5 parameter, correct U5=001.1, press A/M button to enter U6 parameter.
- ◆ Skip parameter U5, U6, U8 to enter into Ua.
- ◆ "Ua" is the zero-position setting of output current: During setting, press ▲ and ▼ to set output 4mA or other value. The value will be corresponding to the zero-position output signal value of actuator, press A/M button to confirm and then enter into Ub parameter.
- ◆ "Ub" parameter output current range setting: Press ▲ and ▼ to set the output 20mA or other value. The value will be corresponding to the full-position output signal value of actuator, press A/M button to confirm and then enter into Uc parameter.
- ◆ "Uc" parameter is to modify the temperature inside the cover. Press ▲ and ▼ for adjustment.
- ◆ Press A/M button for confirmation. Then return to "U5" parameter. Modify "U5" value, make U5=000.5. Press A/M button to confirm and back to test status.

## Failure and Countermeasure

Failure Status	Reason	Countermeasure	
Motor doesn't rotate	The power supply and voltage is low, or no power supply	Check power and voltage	
	Input signal suspends or the value is not enough	Check input signal	
	Break line is separated from terminal stand	Connect wire and replace terminal stand	
	Temperature protector works	Lower the ambient temperature	
		Reduce use frequency	
		Load is too heavy	
	Limit switch actions at the middle openness	Adjust stroke blocker	
	Capacity used for motor enter-phase is damaged	Replace the capacity	
Motor is disconnected	Replace the motor		
Control box is damaged	Replace the control box		
The openness varies continuously	There is interruption signal in signal source	Check input signal	
	The interruption is produced from potentiometer	Replace potentiometer	
	The gear of potentiometer or opening are loosened	Check screw of tightening gear	
The input signal doesn't conform with opening	Input signal is wrong	Check input signal	
	Adjustment of zeroing, multiplying-power has problem	Readjust multiplying-power to zero position	
	Position of potentiometer gear is changed	Readjust the potentiometer gear	
No opening signal	Opening signal line is disconnected or connection has problem	Check wiring	

### GUARANTEE

All valves are guaranteed against any manufacturing defects for a period of 12 months from date of supply, provided the valves have not been misused, damaged or installed for services they are not recommended. The company shall be liable to furnish part / parts thereof or full valve as the company may deem fit.

## V.A. VALVES

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